

T-41-73

GP1A16R

OPIC Photointerrupter with Encoder Function

Features

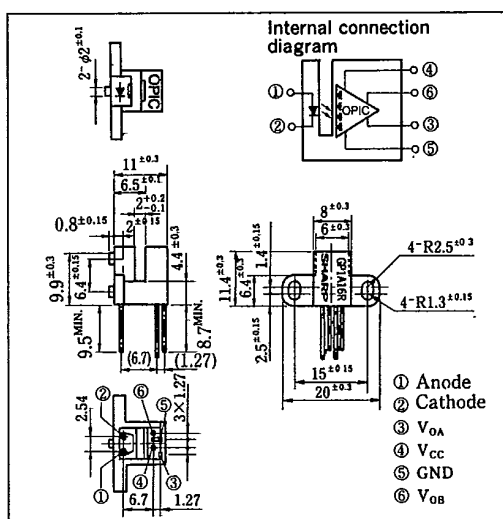
1. 2-phase (A, B) digital output
2. High sensing accuracy
(Disk slit pitch: 0.7mm)
3. TTL compatible output
4. Compact

Applications

1. Electronic typewriters, printers
2. Robots
3. Numerical control machines

Outline Dimensions

(Unit : mm)



※ OPIC is a registered trademark of Sharp and stands for Optical IC. It has a light detecting element and signal processing circuitry integrated onto a single chip.

Absolute Maximum Ratings

(Ta=25°C)

Parameter	Symbol	Rating	Unit
Forward current	I_F	50	mA
*1 Peak forward current	I_{FM}	1	A
Reverse voltage	V_R	6	V
Power dissipation	P	75	mW
Supply voltage	V_{CC}	7	V
Low level output current	I_{OL}	20	mA
Power dissipation	P_o	250	mW
Operating temperature	T_{opr}	0 ~ +70	°C
Storage temperature	T_{stg}	-40 ~ +80	°C
*2 Soldering temperature	T_{sol}	260	°C

*1 Pulse width $\leq 100\mu s$, Duty ratio = 0.01

*2 For 5 seconds

Electro-optical Characteristics

(Unless otherwise specified, Ta=0 ~ +70°C)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Forward voltage	V_F	Ta=25°C, $I_F=20mA$	—	1.2	1.4	V
Reverse current	I_R	Ta=25°C, $V_R=3V$	—	—	10	μA
Operating supply voltage	V_{CC}		4.5	5.0	5.5	V
High level output voltage	V_{OH}	$V_{CC}=5V$, $I_F=20mA$ *3	2.4	4.9	—	V
Low level output voltage	V_{OL}	$I_{OL}=8mA$, $V_{CC}=5V$, $I_F=20mA$ *3	—	0.1	0.4	V
Supply current	I_{CC}	$I_F=20mA$, $V_{CC}=5V$ *4	—	5	20	mA
Duty ratio	D_A *5	$V_{CC}=5V$, $I_F=20mA$ *3	0.20	0.50	0.80	—
Response frequency	f_{MAX}	$f=2.5kHz$, $V_{CC}=5V$, $I_F=20mA$ *3	—	—	10	kHz

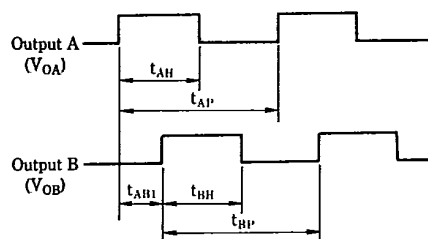
*3 Measured under the condition shown in Measurement Conditions

*4 In the condition that outputs A and B are low level.

*5 $D_A = \frac{t_{AH}}{t_{AP}}$, $D_B = \frac{t_{BH}}{t_{BP}}$

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Output Waveforms



Rotational direction: Counterclockwise when seen from OPIC light detector

Fig. 1 Forward Current vs. Ambient Temperature

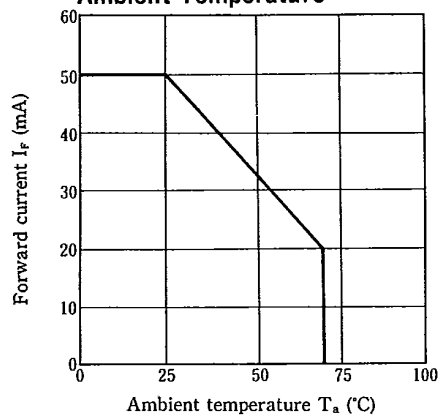


Fig. 2 Output Power Dissipation vs. Ambient Temperature

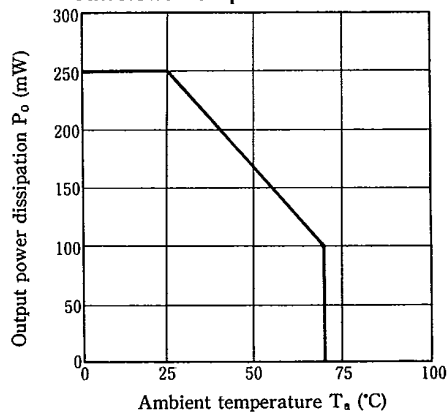


Fig. 3 Duty Ratio vs. Frequency

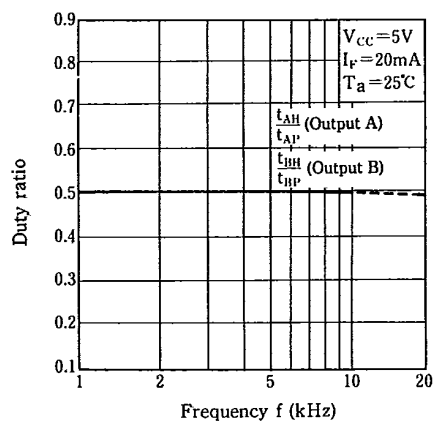
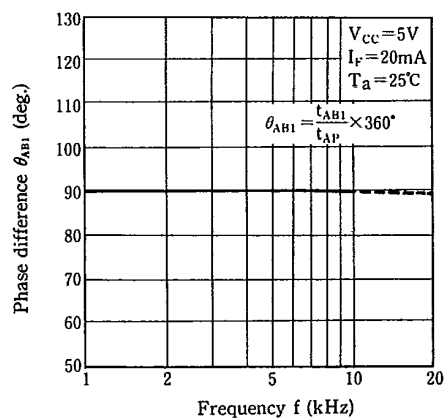
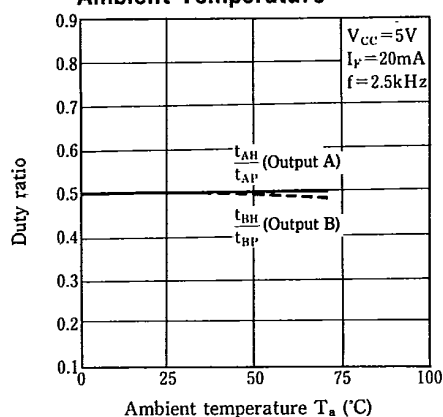
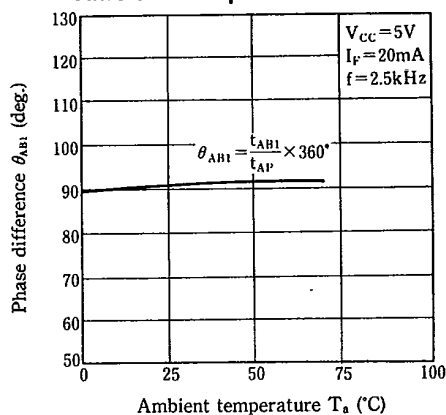
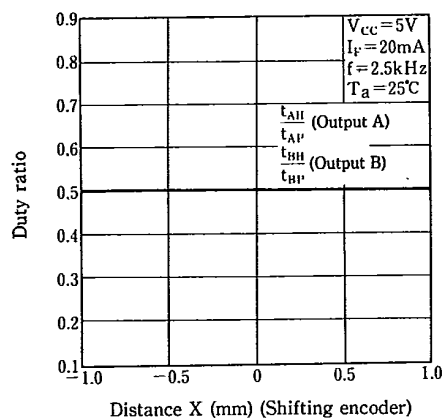
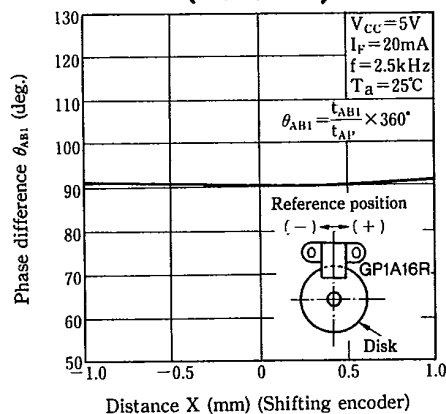
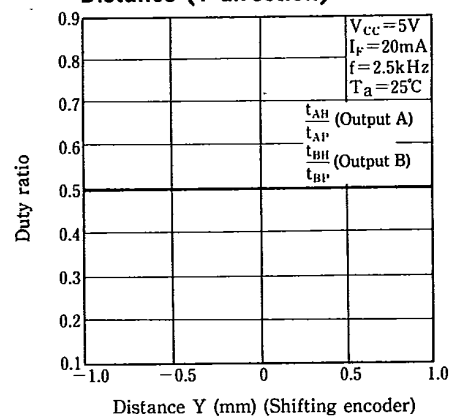
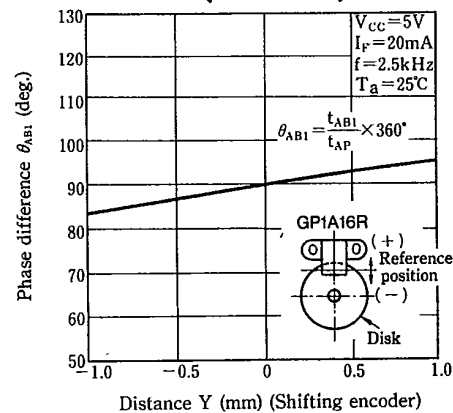


Fig. 4 Phase Difference vs. Frequency



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Fig. 5 Duty Ratio vs. Ambient Temperature**Fig. 6 Phase Difference vs. Ambient Temperature****Fig. 7 Duty Ratio vs. Distance (X direction)****Fig. 8 Phase Difference vs. Distance (X direction)****Fig. 9 Duty Ratio vs. Distance (Y direction)****Fig. 10 Phase Difference vs. Distance (Y direction)**

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Fig. 11 Duty Ratio vs. Distance (Z direction)

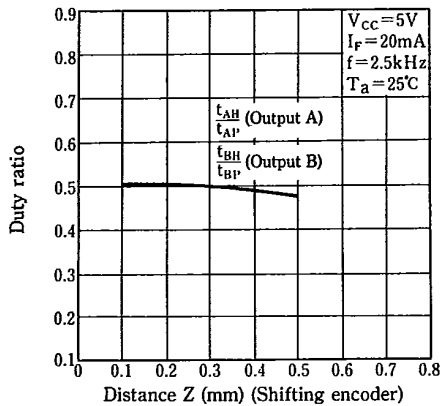
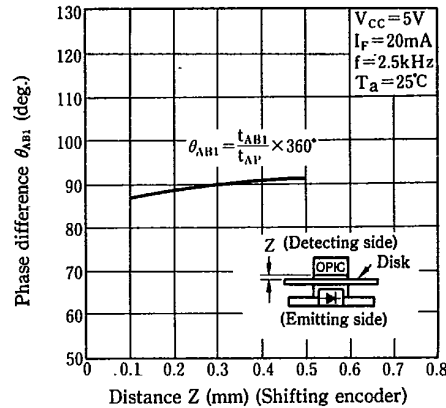
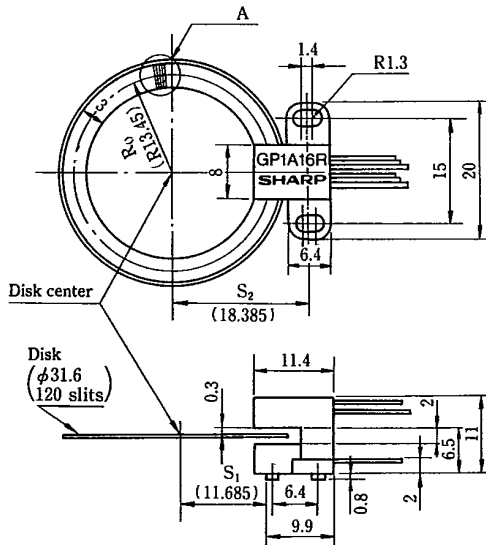


Fig. 12 Phase Difference vs. Distance (Z direction)



Measurement Conditions



< Basic Design >

R_0 (distance between the disk center and half point of a slit),
P (slit pitch), S_1 and S_2 (installing position of photointerrupter)
will be provided by the following equations.

Slit pitch: P (slit center)

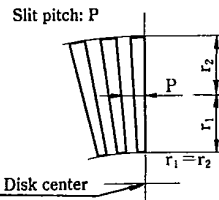
$$R_0 = \frac{N}{120} \times 13.45 \text{ (mm)} \quad N: \text{number of slits}$$

$$P = \frac{2\pi R_0}{N}$$

$$S_1 = R_0 - 1.765 \text{ (mm)} \quad S_2 = S_1 + 6.7 \text{ (mm)}$$

Note) When the number of slits is changed, values in parenthesis
are also changed according to the number.

Enlarged drawing
of A portion



(Ex.) In the case of 200P/R

$$R_0 = \frac{200}{120} \times 13.45$$

$$= 22.42 \text{ mm}$$

$$P = \frac{2 \times \pi \times 22.42}{200}$$

$$= 0.704 \text{ mm}$$

$$S_1 = 22.42 - 1.765$$

$$= 20.655 \text{ mm}$$

$$S_2 = 20.655 + 6.7$$

$$= 27.355 \text{ mm}$$

Disk is optional.

Following types are available.

Model No.	Resolution (P/R)
GP1P16RA	120
GP1P16RB	200

(Precautions for Use)

Note 1) In order to stabilize power supply line, connect a
by-pass capacitor of more than $0.01\mu\text{F}$ between
 V_{cc} and GND near the device.

Note 2) This module is designed to be operated at $I_f =$
20mA TYP.